Enhancing Simulation Models for Open Pit Copper Mining
Using Visual Basic for Applications

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ABSTRACT:
In open pit mining operations, the diesel consumption of haul trucks represents roughly 50% of the total operating costs. To reduce operating costs, the trucks must be allocated and dispatched efficiently. In this study, a simulation model of open pit copper mining has been enhanced using Visual Basic for Applications (VBA) programming, which can be used to test and create a truck dispatching control table to satisfy a mining plan. By combining the simulation technique with the utilization of Excel and VBA programming, the enhanced simulation model could aid managers in mining operations decisions.

KEYWORDS: Open Pit Mining, Simulation, Truck Dispatching, VBA Programming

1 INTRODUCTION
In open pit mining operations, haul trucks’ diesel consumption accounts for the largest portion of operating costs. As other studies have demonstrated, transportation costs represent roughly 50% of the operating costs in an open pit mine (Alarie and Gamache, 2002; Ercelebi and Bascetin, 2009). In this context, the trucks must be efficiently allocated and dispatched to reduce operating cost.

An open pit copper mine usually comprises two major components, the open pit mining operation and the copper ore enrichment plant. At present, the mining industry is a strong foundation of Mongolian economic growth. In 2007, according to the Mongolian Statistical Yearbook, Mongolia’s overall GDP grew by 8.4% and that of the mining sector grew by 2.7%. High international gold and copper prices have driven exploitation of new mines and increased this sector’s production. The mining industry is required to flexibly respond to trends in world market demands, and companies must improve their mining operations and transportation of mined products.

This study applies computer simulation techniques to support open pit mining operations management. After a brief description of the simulation’s application in the mining industry, we present a case study utilizing simulation techniques to solve an open pit mine truck dispatching problem. Simulation models are constructed and applied by utilizing GPS (Global Positioning System) tracking data to evaluate the current state of operations for an open pit mining company. Then, the simulation model is enhanced with Excel and Visual Basic for Applications (VBA) programming, which enable testing and creation of a truck dispatching control table to satisfy a mining plan.
2 OPERATIONS AND SIMULATION IN THE MINING INDUSTRY

There are two general approaches to mining: open pit (i.e., surface) mining and underground mining. The mining industry faces problems that are growing in both size and complexity. Production is dependent on the geological position of the ore body and the technology for extraction, which involves the use of expensive capital equipment. Simulations can support management decisions for daily production and capital expenditures, providing a visual and dynamic demonstration of system behavior optimization through various strategies (Chinbat and Takakuwa, 2009).

In the open pit mining operation, a materials handling system consists of subsystems for loading, hauling, and dumping. Truck haulage is the most common means of moving ore/waste in open pit mining operations, but is also the most expensive unit of operation in a truck-shovel mining system (Kolojna et al., 1993). Bauer and Calder (1973) noted that the complexity of modern open pit load-haul-dump systems requires realistic working models. Nenonen et al. (1981) studied an interactive computer model of truck-shovel operations in an open pit copper mine. Qing-Xia (1982) studied a computer simulation program of drill rigs and shovel operations in open pit mines.

As Subtil et al. (2011) states, “In the specific context of the mining industry, the truck dispatch problem in open pit mining is dynamic and consists in answering the following question: ‘Where should this truck go when it leaves this place?’” Two goals were targeted to solve the dispatching problems: increase productivity and reduce operating costs (Alarie and Gamache, 2002). Burt et al. (2005) conducted a critical analysis of the various models used for surface mining operations, identifying important constraints and suitable objectives for an equipment selection model. They used a new mixed integer linear programming (LP) model that incorporates a linear approximation of the cost function. Fioroni et al. (2008) proposed concurrent simulation and optimization models to achieve a feasible, reliable, and accurate solution to the analysis and generate a short-term planning schedule. Ercelebi and Bascetin (2009) studied truck-shovel operation models and optimization approaches for allocating and dispatching truck under various operating conditions. They used the closed queuing network theory for truck allocation and LP to dispatch trucks to shovels. Boland et al. (2009) proposed LP-based disaggregation approaches to solve a production scheduling problem in open pit mining. Subtil et al. (2011) proposed a multistage approach for dynamic truck dispatching in real open pit mine environments, implementing it with a commercial software package.

3 OPEN PIT MINING OPERATION

3.1 System Description of a Mongolian Open Pit Mining Company

Company A is one of the largest ore mining and processing companies in Asia. Similar to most mining plants, company A’s production process comprises two major components, an open pit mine and a copper ore enrichment plant. The mine and factory are located in Mongolia and have been in continuous operation since 1978. Both the open pit and enrichment plant operate and produce 24 hours a day throughout the year. At present, company A processes 25 million tons of ore per year and produces over 530 thousand tons of copper concentrate and roughly three thousand tons of molybdenum concentrate annually. The following case study is part of a wider joint research project with company A, with the goal of improving mining and transportation operations efficiency in an open pit mine and ore enrichment plant.
During years of mining, the contents of copper and molybdenum have decreased. Further, in this open pit mine, the contents of copper and molybdenum vary according to the mining location's altitude. Specifically, the copper content is lower at low-altitude mining points, where there has been deep digging. However, ore with a copper content below 0.25% cannot be processed under the enrichment plant’s current technical conditions. Therefore, from the operational management perspective, that is, to preserve the product quality and maintain stable throughput, the copper content of the ore fed to the enrichment plant must remain within required parameters roughly. Therefore, before feeding the ore into the enrichment process, the ores with initially high and low contents of copper must be mixed.

A few years ago, company A implemented a control system for mining transportation with GPS technology. This transportation control system helps company A to technically and economically control the loading and transportation processes.

3.2 Mining Planning

The mining planning stage is crucial in any type of mining because it seeks costs reduction and maximized production plans and focuses on quality and operation requirements, asset utilization, such as trucks, and tractors, and restraints, such as those faced during shoveling (Fioroni et al., 2008). Figure 1 presents a simplified process map for company A’s open pit mine operation. In company A, when creating a mining plan in accordance with a production plan, that plan must include ores containing both low and high copper content. In company A, the geologist group develops the mining site plan. The open pit mining plan is based on the annual plan, which specifies the volume to excavate from the current altitude of the open pit and evenly distributes the rest to the different altitudes of the mine. The plan also considers the following factors: ore volume, concentrate and oxide levels, and primary ore percentage; geological plan and strategy; ore processing standards; and technology of the
Table 1: An example of a week’s completed mining plan

<table>
<thead>
<tr>
<th>Elevation of the No. of Mining Points</th>
<th>No. of Excavators</th>
<th>Ore (tons)</th>
<th>Disposal Soil (tons)</th>
<th>Content of Cu in Ore (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1355</td>
<td>16</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>1355</td>
<td>17</td>
<td>126</td>
<td>163,281</td>
<td>-</td>
</tr>
<tr>
<td>1355</td>
<td>12</td>
<td>85,067</td>
<td>-</td>
<td>0.54</td>
</tr>
<tr>
<td>1325</td>
<td>14</td>
<td>146,917</td>
<td>7,681</td>
<td>0.52</td>
</tr>
<tr>
<td>1310</td>
<td>15</td>
<td>7,651</td>
<td>108,919</td>
<td>0.57</td>
</tr>
<tr>
<td>1310</td>
<td>16</td>
<td>61,564</td>
<td>48,889</td>
<td>0.44</td>
</tr>
<tr>
<td>1295</td>
<td>18</td>
<td>113,964</td>
<td>9,809</td>
<td>0.42</td>
</tr>
<tr>
<td>1295</td>
<td>20</td>
<td>87,966</td>
<td>47,635</td>
<td>0.49</td>
</tr>
<tr>
<td>1280</td>
<td>19</td>
<td>90,415</td>
<td>36,398</td>
<td>0.68</td>
</tr>
<tr>
<td>Total</td>
<td></td>
<td>593,670</td>
<td>422,612</td>
<td>0.53</td>
</tr>
</tbody>
</table>

Table 1 shows an example of a completed mining plan for a given week. Enrichment plant and excavation standard. Therefore, open pit mine planning relates to the output amount of the production plan for the enrichment factory. It is difficult to determine the best mining positions by considering the required percentage of copper and molybdenum contents, required to satisfy the operations planning of a successful refinery. Table 1 shows an example of a completed mining plan for a given week.

3.3 Transportation and Truck Dispatching

As stated, material (ore and waste soil) transportation in an open pit mine consumes roughly 50% of total operating costs. In this context, efficient truck allocation and dispatching represents a considerable saving of resources. However, the problem of dispatching trucks to excavators is more difficult than it appears.

Table 2 summarizes company A’s transportation resources. It owns 24 dump trucks, all of which can transport ore or soil from mining points to the enrichment plant or disposal hills, respectively, per the operation center’s instructions. At the 13 soil disposal locations (hills) around the open pit mining location, the soil is spread over the ground using a bulldozer to recover the environment. The enrichment plant has two ore feeding entrances. When the ore reaches the enrichment plant, it is fed into an ore feeding entrance (bunker A or B) depending upon the size (the diameter) of the ore, and the plant performs the concentrating processes. Table 2 briefly presents the parameters of

Table 2: Company A’s transportation resources

<table>
<thead>
<tr>
<th>Drillers</th>
<th>Number of Units Held</th>
<th>5 units</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of Operation Shifts</td>
<td>2 shifts</td>
<td></td>
</tr>
<tr>
<td>Bulldozers</td>
<td>Number of Units Held</td>
<td>8 units</td>
</tr>
<tr>
<td>Number of Operation Shifts</td>
<td>3 shifts</td>
<td></td>
</tr>
<tr>
<td>Average Productivity per Hour</td>
<td>331.4 m³/h **</td>
<td></td>
</tr>
<tr>
<td>Excavators</td>
<td>Number of Units Held</td>
<td>24 units</td>
</tr>
<tr>
<td>Number of Operation Shifts</td>
<td>3 shifts</td>
<td></td>
</tr>
<tr>
<td>Average Distance in a One-way Transportation</td>
<td>3.26 km **</td>
<td></td>
</tr>
<tr>
<td>Average Velocity when Loading</td>
<td>24 km/h</td>
<td></td>
</tr>
<tr>
<td>Average Velocity when Unloading</td>
<td>40 km/h</td>
<td></td>
</tr>
<tr>
<td>Operators</td>
<td>30</td>
<td></td>
</tr>
<tr>
<td>Dump Trucks</td>
<td>Number of Units Held</td>
<td>130 tons</td>
</tr>
<tr>
<td>Capacity</td>
<td>TRIA(90,130,147) tons</td>
<td></td>
</tr>
<tr>
<td>Amount per Transportation</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Average Distance in a One-way Transportation</td>
<td>3.26 km **</td>
<td></td>
</tr>
<tr>
<td>Average Velocity when Loading</td>
<td>24 km/h</td>
<td></td>
</tr>
<tr>
<td>Average Velocity when Unloading</td>
<td>40 km/h</td>
<td></td>
</tr>
<tr>
<td>Operation Shifts</td>
<td>3 shifts</td>
<td></td>
</tr>
<tr>
<td>Operators</td>
<td>80</td>
<td></td>
</tr>
<tr>
<td>Shifts</td>
<td>8:00-16:00</td>
<td></td>
</tr>
<tr>
<td>Shift No.1</td>
<td>16 00-24:00</td>
<td></td>
</tr>
<tr>
<td>Shift No.2</td>
<td>24 00-08:00</td>
<td></td>
</tr>
</tbody>
</table>

Note: * Measures actually vary.
** TRIA indicates a triangular distribution.
certain measures as averaged values.

Although the GPS technology’s transportation control information system primarily functions to control fuel consumption, weight capacity, and speed of the dump trucks, dispatching a truck to an excavator has not yet been automated due to the complexity involved in dispatching trucks. As described above, to maintain continuous production in the enrichment plant, the content of ore fed to the plant must be kept approximately constant to the required average, a challenging goal. As Table 1 shows, different mining points and locations have different copper content. When calculating the dispatching of a truck to an excavator, dispatchers must determine the truck’s optimal destination to satisfy the production requirements and its transportation amount. Simultaneously, the dispatchers must consider the progress of transportation at each mining point, because to satisfy the entire mining plan’s specifications, both the transportation of ore and waste soil must be completed on schedule. Currently, the transport control staff dispatches trucks manually using wireless walkie-talkies and information from the GPS transportation control information system, which is displayed on their computer monitor in real time.

In this study, to facilitate fleet management in open pit mining, we attempt to embed the logic of truck dispatching and automate the dispatching systems. Thus, after the mining plan is complete, when we run the model, the program automatically generates the truck dispatch control table.

4 DEVELOPMENT AND ANALYSIS OF THE SIMULATION MODEL

4.1 Parameters and Construction of the Simulation Model

Simulations can provide a visual and dynamic system operation description to help mining project managers understand the system’s behavior and optimize it through various strategies (Chinbat and Takakuwa, 2009). We apply the computer simulation technique to support operations management in company A. The simulation model is programmed in Arena (Kelton et al., 2010) and overlaid on a scaled mine layout. As described, company A has implemented a mining transportation control system with GPS technology. The GPS tracking data and other associated information update the simulation at 1-minute intervals; the important parameters, such as the truck location, its fuel level, and load weight are shown on the open pit map.

Figure 2 illustrates the overall structure and flow of the simulation model. To understand the current (As-Is) state of mining operations, we initially construct the As-Is model as the basis for experimental analysis. Then, to estimate company A’s maximum mining capacity, we construct an experimental model for capacity testing. Tan and Takakuwa (2012) presented details on the construction and analysis of the simulation model for company A. Figure 3 illustrates a screen image for running the As-Is simulation model. In this study, we focus on integrating

Figure 2: Overall structure and simulation model flow
the Arena simulation model with Excel and VBA for automatic truck dispatching.

4.2 Integrated Arena Simulation Model with VBA

Microsoft VBA represents a powerful development in technology that rapidly customizes software applications and integrates them with existing data and systems (Miwa and Takakuwa, 2005). Arena permits the model developer to use VBA if the model file is loaded, executed, or terminated, or if entities flow through the Arena model modules (Seppanen, 2000). By using Arena VBA, the simulation model can also communicate with other applications such as Microsoft Excel and Access. By combining the simulation capabilities of Arena and VBA, we can construct a customized, dynamic, and flexible integrated simulation model. Some examples of using Arena and VBA to develop customized complex simulation models can be found in Kelton et al (2010), Seppanen (2000), and Miwa and Takakuwa (2005).

4.3 Dynamic Truck Dispatch using VBA Programming

Subtil et al. (2011) proposed an algorithm for the problem of dynamic truck dispatching in open pit mining, with two main phases: allocation planning and dynamic allocation. Allocation planning determines the mine’s maximum capacity in the current scenario and the optimal size of the fleet of trucks needed for this capacity. Because company A’s maximum mining capacity and optimal fleet size have been discussed and found (Tan and Takakuwa, 2012), the present study draws on the earlier study’s dynamic allocation process.

According to Subtil et al. (2011), in the second phase, dynamic allocation determines the best allocation scheduler for a dispatch requisition to comply with the allocation planning using a dynamic

![Algorithm for calculating load capacity when dispatching trucks to excavators](image)

Figure 3: As-Is model animation

Figure 4: Algorithm for calculating load capacity when dispatching trucks to excavators
dispatch heuristic. Figure 4 presents an algorithm for calculating the optimal loading amount when dispatching trucks to excavators. To illustrate this algorithm, for convenience, we provide a simple example. At the mining point Z, the content of copper contained in the ore is 0.60%. To maintain stable production in the enrichment plant, the ore must be stable and continuous at the averaged content of 0.53%. Thus far, 100 tons of ore have been transported to the bunker and the averaged copper content in the bunker is currently 0.48%. The question is how much ore with 0.6% copper content should be transported to the bunker? Here, the maximum load capacity of the truck is 130 tons.

To solve the optimal transportation amount of 0.6% copper content ore (hereafter, Q), we generate a loop for Q from one ton to 130 tons with one-ton steps. While Q is looping, we calculate and estimate the copper content (hereafter, Cu%) after Q tons of 0.6% ore content being fed to the bunker, and calculate the error between 0.53% and Cu%. Then, the Q yielding the smallest value of this error solves the problem.

To verify the effectiveness of the proposed dynamic dispatch method, we revised the As-Is model to another experimental model with Arena VBA programming. Figure 5 displays a section of this VBA procedure’s code.

### 4.4 Simulation Experiment and Results

After building the simulation model, we validated it through an interactive process between the company staff and the modeler. This interactive process compared the model’s output with the actual GPS tracking data. After confirming the model’s reliability, we ran the simulations and analyzed the results. Table 3 displays the results of comparison between the manual and proposed VBA enhanced dynamic dispatch methods. Table 3’s values are averaged execution results at the 95% confidence interval. We executed the simulation for 10 replications. Figure 6 presents a portion of the truck dispatch control table output by the VBA enhanced simulation model, which can be used to achieve the mining plan.

The results shown in Table 3 demonstrate that the VBA enhanced dynamic dispatch method improves the performance indicators’ values. First, the simulation’s duration, as well as the time taken to complete the

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Table 3: Comparing results of manual dispatching and VBA enhanced dynamic dispatch method

<table>
<thead>
<tr>
<th>Performance Indicators</th>
<th>Dynamic Dispatched Method with VBA</th>
<th>Manual Dispatching (Historic Value)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Expected Excavation Plan of Ore (tons)</td>
<td>953,670</td>
<td>11,423</td>
</tr>
<tr>
<td>Expected Excavation Plan of Waste (tons)</td>
<td>422,612</td>
<td>123,72</td>
</tr>
<tr>
<td>The Length of Simulation / Total Time Taken to Complete the Expected Excavation Plan (min.)</td>
<td>11,542 - 11,594</td>
<td>11,502</td>
</tr>
<tr>
<td>Number of Transportations (round trips)</td>
<td>593,670</td>
<td>593,670</td>
</tr>
<tr>
<td>Total Weight of the Transported Ore (tons)</td>
<td>422,612</td>
<td>422,612</td>
</tr>
<tr>
<td>Total Weight of the Transported Waste (tons)</td>
<td>422,612</td>
<td>422,612</td>
</tr>
<tr>
<td>Average Weight of Loading per Transportation (tons)</td>
<td>122</td>
<td>122</td>
</tr>
<tr>
<td>Average Transportation Time Spent in a Single Trip (min.)</td>
<td>45.0 - 45.62</td>
<td>11.8</td>
</tr>
<tr>
<td>Total Transportation Distance of Ore (km)</td>
<td>12362</td>
<td>12362</td>
</tr>
<tr>
<td>Total Transportation Distance of Waste (km)</td>
<td>8267</td>
<td>8267</td>
</tr>
<tr>
<td>Average Truck Scheduled Utilization (%)</td>
<td>99.73</td>
<td>99.73</td>
</tr>
</tbody>
</table>

---
Private Sub VBA_Block_12_ _Fire()
Set s = ThisDocument.Model.SIMAN
Dim myStation As Arena.station
Dim MinimumContentGosa As Single

DesiredContentCu = 0.53 'planned copper content
myDistance_to_KKD = s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Distance to KKD"))
myDistance_to_KCI = s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Distance to KCI"))
myDistance_to_Disposal4 = s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Distance to Disposal 4"))
myWeight = 120 'set as a provisional value
myNet_Cu_atDestination = s.VariableArrayValue(s.SymbolNumber("Net_Cu_KKD"))
myNet_Cu_atDestination = s.VariableArrayValue(s.SymbolNumber("Net_Cu_KCI"))
myOreTransportedtoDestination = s.VariableArrayValue(s.SymbolNumber("Ore Transported to KCI"))
myOreTransportedtoDestination = s.VariableArrayValue(s.SymbolNumber("Ore Transported to KKD"))

If myEntitytype = 1 Then
    'send to bunker KCI
    myDestinationIndex = 3  'To sent the transportation destination to Bunker KCI
    myDestinationIndex = 4  'To sent the transportation destination to Bunker KKD
ElseIf myEntitytype = 2 Then
    'When the entity type is Ore
    If myEntitytype = 1 Then
        'When the entity type is Soil
        myOreTransportedtoKCI = s.VariableArrayValue(s.SymbolNumber("Ore Transported to KCI"))
        myOreTransportedtoKKD = s.VariableArrayValue(s.SymbolNumber("Ore Transported to KKD"))
        myWeight = 120 'set as a provisional value
End If
End If

If myDistance_to_KKD > 0 Then  '## When the disposal hill No.4 is further
    myDestinationIndex = 5  '## To sent the transportation destination to Disposal hill No.4
ElseIf myEntitytype = 2 Then  '## send to bunker KKD
    myDestinationIndex = 3  '## To sent the transportation destination to Bunker KKD
End If

If myEntitytype = 1 Then
    'When the entity type is Soil
    myDistance_to_KCI > 0 Then  '## When the disposal hill No.4 is further
        myDestinationIndex = 6  '## To sent the transportation destination to Disposal hill No.5
    ElseIf myEntitytype = 2 Then  '## Send to Bunker KKD
        myDestinationIndex = 3  '## To sent the transportation destination to Bunker KKD
    End If
End If

For i = 60 To 130 Step 1
    MiniumContentGosa = (130 * myContent_Cu + myNet_Cu_atDestination) / (OreTransportedtoDestination + 130)
   EstimatedContentCu = (i * myContent_Cu + myNet_Cu_atDestination) / (OreTransportedtoDestination + i)
    NowContentGosa = Abs(EstimatedContentCu - DesiredContentCu)
    If NowContentGosa <= MiniumContentGosa Then
        EstimatedContentCu = (i * myContent_Cu + myNet_Cu_atDestination) / (OreTransportedtoDestination + i)
        NewContentGosa = Abs(EstimatedContentCu - DesiredContentCu)
        OptimizationLoad = i
        Next i
    End If
End For

ElseIf myEntitytype = 2 Then
    'When the entity type is Ore
    s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("content_Cu")) = 1
    s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Priority12")) = 3
    s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Priority14")) = 1
    s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Priority15")) = 1
    s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Priority16")) = 1
    s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Priority17")) = 1
    s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Priority18")) = 1
    s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Priority19")) = 1
    s.EntityAttribute(s.ActiveEntity, s.SymbolNumber("Priority20")) = 1
End If
Next i

EstimatedContentCu = (i * myContent_Cu + myNet_Cu_atDestination) / (OreTransportedtoDestination + i)
NewContentGosa = Abs(EstimatedContentCu - DesiredContentCu)

End If
End If
End Sub

Figure 5: VBA procedure for truck dispatching and calculating optimal loading amount
Figure 6: Truck dispatching table output by VBA enhanced simulation model (partial)

expected mining plan, significantly decreased from 11,502 to 7,286 minutes. Thus, company A can use the time saved to expand their production. In addition, the total number of ore and waste transportation rounds and distances decrease. Because the trucks consume a large amount of gasoline, these transportation reductions will directly reduce transportation costs.

5 CONCLUSION

In this study, simulation models were constructed and enhanced with VBA programming to test and create a dynamic dispatch control table that satisfies an open pit mining plan. Results demonstrated that by combining the simulation technique with Excel and VBA programming, trucks’ transportation performance could be significantly improved, thus reducing transportation costs. Simulations can help mining project managers understand the system’s behavior by providing visual and dynamic descriptions, allowing them to optimize the system through appropriate strategies.

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